

# GCLC, Construction Problems, Coherent Logic and All That

Predrag Janičić

[www.matf.bg.ac.rs/~janicic](http://www.matf.bg.ac.rs/~janicic)

Automated Reasoning GrOup (ARGO)

Faculty of Mathematics

University of Belgrade, Serbia

University of Strasbourg, France, July 19, 2012.

# Faculty of Mathematics, University of Belgrade

- University of Belgrade (<http://www.bg.ac.rs>)
  - Established in early 1800's
  - One of the oldest and largest in the region
  - Around 90000 students and 4000 members of teaching staff
- Faculty of Mathematics (<http://www.matf.bg.ac.rs>)
  - Around 1500 students and 80 members of teaching staff
  - Departments for pure mathematics, computer science, astronomy...

# Automated Reasoning GrOup (ARGO)

- Area:
  - automated theorem proving
  - decision procedures/SAT/SMT
  - interactive theorem proving (Isabelle)
  - geometry reasoning
- 9 members
- More at: <http://argo.matf.bg.ac.rs/>

# Automated Reasoning GrOup (ARGO) — People



Predrag Janičić



Filip Marić



Sana Stojanović



Danijela Petrović



Vesna Marinković



Ivan Petrović



Mladen Nikolić



Milan Banković



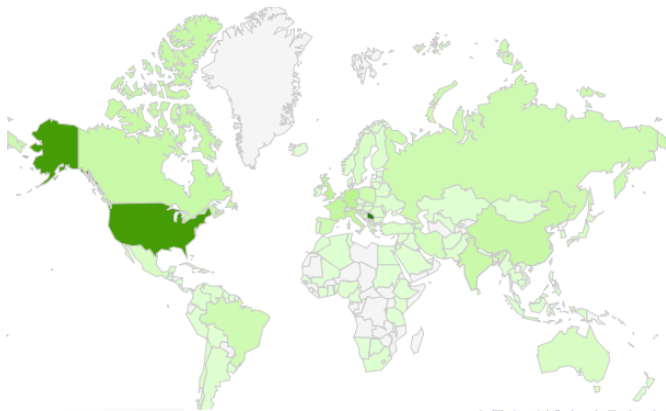
Mirko Stojadinović

## GCLC Tool — Main Applications

- GCLC: a geometry tool for
  - mathematical education
  - producing high-quality mathematical illustrations (export to different formats)
  - storing mathematical contents
  - studies of automated geometrical reasoning
- First version released in 1996, still maintained
- Versions for Windows and Linux, freely available from <http://www.matf.bg.ac.rs/~janicic/gclc>

## GCLC — Users

- Thousands of users, used in high-schools and university courses, and for publishing worldwide



## GCLC: Basic Principles

- A construction is a formal procedure, not an image
- GCLC uses a custom geometry language and procedural specifications of geometry figures
- Images can be produced from descriptions, but not vice-versa!
- All instructions are given explicitly, in GCLC language
- Instructions for describing **contents**
- Instructions for describing **presentation**

# GCLC Language

- Support for geometrical primitive constructions, compound constructions, transformations, etc.
- Symbolic expressions, while-loops, user-defined procedures
- Conics, 2D and 3D curves, 3D surfaces



# Example

The screenshot shows the WinGCLC application window with the following content:

```
WinGCLC - [barycenter.gcl]
File Edit Source Picture View Window Help
dim 100 45
point A 20 7
point B 80 7
point G 57 18
midpoint M_c A B
towards C M_c G 3
drawdashsegment M_c C
drawsegment A B
drawsegment A C
drawsegment B C
cmark_b A
cmark_b B
cmark_r C
cmark_l G
cmark_b M_c
midpoint M_b A C
prove ( collinear G M_b B )
```

The diagram on the right shows a triangle with vertices A, B, and C. Point M<sub>c</sub> is the midpoint of segment AB. A dashed line segment connects M<sub>c</sub> and C. Point G is located on segment AC. The goal is to prove that G, M<sub>b</sub>, and B are collinear.

Output window:  
B : POINT : (80.00,7.00)  
A : POINT : (20.00,7.00)  
File successfully processed.

Status bar: Ready Ln 22, Col 29 | x=23.40 | y=56.00 | Zoom:1.44 | NUM

## Theorem Provers Built-into GCLC

- There are three theorem provers built-into GCLC:
  - a theorem prover based on the area method (Chou et.al 1992)
  - a theorem prover based on the Wu's method (Wu 1977)
  - a theorem prover based on the Gröbner bases method (Buchberger 1965)
- Deal with conjectures that corresponds to properties of constructions
- All provers are very efficient and can prove many non-trivial theorems in only milliseconds.
- The theorem provers are tightly built-in: the user has just to state the conjecture, for example:  
`prove { identical 01 02 }`

## Processing Specifications of Constructions

- Syntactical check
- Semantical check (e.g., whether two concrete points determine a line)
- Deductive check — verifies if a construction is regular (e.g., whether two constructed points never determine a line)

# Synthesizing Constructions

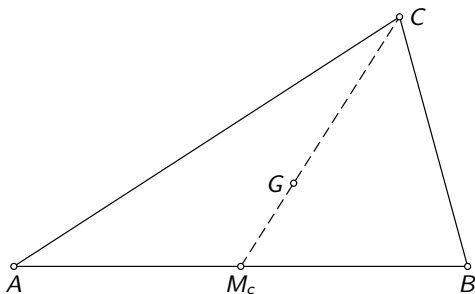
- Checking correctness of constructions is all fine...
- ...but can be automate synthesizing of constructions
- Our approach next to be presented (joint work with Vesna Marinković)

## Example Problem



**Problem:** *Construct a triangle  $ABC$  given vertices  $A$  and  $B$  and the barycenter  $G$*

## Example Solution



**Construction:** Construct the midpoint  $M_c$  of the segment  $AB$ ;  
then construct the vertex  $C$  such that  $M_cG : M_cC = 1/3$

# Existing Approaches and Corpora

- Several existing approaches, including:
  - Schreck (1995)
  - Gao and Chou (1998)
  - Gulwani et al. (2011)

## Wernick's Corpus

- One of systematically built corpora, created in 1982, some variants in the meanwhile
- **Task:** construct a triangle given three located points selected from the following list:
  - $A, B, C$  – vertices
  - $I, O$  – incenter and circumcenter
  - $H, G$  – orthocenter and barycenter
  - $M_a, M_b, M_c$  – the side midpoints
  - $H_a, H_b, H_c$  – feet of altitudes
  - $T_a, T_b, T_c$  – intersections of the internal angles bisectors with the opposite sides



## Wernick's Problems (2)

139 non-trivial, significantly different, problems; 25 redundant (R) or locus-restricted (L); 72 solvable (S), 16 unsolvable (U); 25 still with unknown status

<b>1. A, B, O</b>	<b>L</b>	57. A, H, I S [9]	85. $M_a, M_b, H_a$ S	113. $M_a, T_b, T_c$
		A, $T_a, T_b$ S [9]	86. $M_a, M_b, H_c$ S	114. $M_a, T_b, I$ U [9]
		$T_a, I$ L	87. $M_a, M_b, H$ S [9]	115. G, $H_a, H_b$ U [9]
<b>2. A, B, <math>M_a</math></b>	<b>S</b>	$T_b, T_c$ S	88. $M_a, M_b, T_a$ U [9]	116. G, $H_a, H$ S
		I S	89. $M_a, M_b, T_c$ U [9]	117. G, $H_a, T_a$ S
		$M_b$ S	90. $M_a, M_b, I$ U [10]	118. G, $H_a, T_b$
<b>3. A, B, <math>M_c</math></b>	<b>R</b>	G S	91. $M_a, G, H_a$ L	119. G, $H_a, I$
		$H_a$ L	92. $M_a, G, H_b$ S	120. G, H, $T_a$ U [9]
		$H_b$ S	93. $M_a, G, H$ S	121. G, H, I U [9]
<b>4. A, B, G</b>	<b>S</b>	S	94. $M_a, G, T_a$ S	122. G, $T_a, T_b$
		L	95. $M_a, G, T_b$ U [9]	123. G, $T_a, I$
		U [9]	96. $M_a, G, I$ S [9]	124. $H_a, H_b, H_c$ S
<b>5. A, B, <math>H_a</math></b>	<b>L</b>	S	97. $M_a, H_a, H_b$ S	125. $H_a, H_b, H$ S
		S	98. $M_a, H_a, H$ L	126. $H_a, H_b, T_a$ S
		R	99. $M_a, H_a, T_a$ L	127. $H_a, H_b, T_c$
<b>6. A, B, <math>H_c</math></b>	<b>L</b>	U [9]	100. $M_a, H_a, T_b$ U [9]	128. $H_a, H_b, I$
		U [9]	101. $M_a, H_a, I$ S	129. $H_a, H, T_a$ L
		$H_b$ U [9]	102. $M_a, H_b, H_c$ L	130. $H_a, H, T_b$ U [9]
<b>7. A, B, H</b>	<b>S</b>	H S	103. $M_a, H_b, H$ S	131. $H_a, H, I$ S [9]
		$H_a, T_a$ S	104. $M_a, H_b, T_a$ S	132. $H_a, T_a, T_b$
		$H_a, T_b$	105. $M_a, H_b, T_b$ S	133. $H_a, T_a, I$ S
<b>8. A, B, <math>T_a</math></b>	<b>S</b>	J, $H_a, I$	106. $M_a, H_b, T_c$ U [9]	134. $H_a, T_b, T_c$
		L, O, H, $T_a$ U [9]	107. $M_a, H_b, I$ U [9]	135. $H_a, T_b, I$
<b>9. A, B, <math>T_c</math></b>	<b>S</b>	80. O, H, I U [9]	108. $M_a, H, T_a$ U [9]	136. H, $T_a, T_b$
		81. O, $T_a, T_b$	109. $M_a, H, T_b$ U [10]	137. H, $T_a, I$
		25. A,	110. $M_a, H, I$ U [10]	138. $T_a, T_b, T_c$ U [11]
		26. A, $M_a, A$ D, I, I S	111. $M_a, T_a, T_b$ U [10]	139. $T_a, T_b, I$ S
		27. A, $M_a, I$ S [9]	112. $M_a, T_a, I$ S	
		28. A, $M_b, M_c$ S		
		55. A, H, $T_b$ S		
		83. $M_a, M_b, M_c$ S		
		84. $M_a, M_b, G$ S		

## Basic Approach (1)

- A careful analysis of all available solutions performed
- Solutions use high-level rules, e.g:
  - *if barycenter  $G$  and circumcenter  $O$  are known, then the orthocenter  $H$  can be constructed*
  - *if two triangle vertices are given, then the side bisector can be constructed*
- In total:  $\approx 70$  rules used

## Basic Approach (2)

- Implemented in Prolog
- Simple forward chaining mechanism for search procedure
- Solves most of solvable examples from Wernick's list in less than 1s and with the maximal search depth 9
- But... **there are too many rules!** (it is not problem to **search over them**, but to **invent and systematize them**)

## Separation of Concepts – Definitions, Lemmas, Construction Steps (1)

**Motivating example:** *Construct the midpoint  $M_c$  of  $AB$  and then construct  $C$  such that  $M_cG : M_cC = 1 : 3$  uses the following:*

- $M_c$  is the side midpoint of  $AB$
- $G$  is the barycenter of  $ABC$
- it holds that  $M_cG = 1/3M_cC$
- given points  $X$  and  $Y$ , it is possible to construct the midpoint of the segment  $XY$
- given points  $X$  and  $Y$ , it is possible to construct a point  $Z$ , such that:  $XY : XZ = 1 : k$

## Separation of Concepts – Definitions, Lemmas, Construction Steps (2)

**Motivating example:** *Construct the midpoint  $M_c$  of  $AB$  and then construct  $C$  such that  $M_cG : M_cC = 1 : 3$  uses the following:*

- $M_c$  is the side midpoint of  $AB$  (definition of  $M_c$ )
- $G$  is the barycenter of  $ABC$  (definition of  $G$ )
- it holds that  $M_cG = 1/3M_cC$  (lemma)
- given points  $X$  and  $Y$ , it is possible to construct the midpoint of the segment  $XY$  (construction primitive)
- given points  $X$  and  $Y$ , it is possible to construct a point  $Z$ , such that:  $XY : XZ = 1 : k$  (construction primitive)

## Advanced Approach

- **Task:** Determine the sets of definitions, lemmas and construction primitives such that all needed high-level (instantiated) construction rules can be built from them
- From:
  - it holds that  $M_c G = 1/3 M_c C$  (lemma)
  - given points  $X$  and  $Y$ , it is possible to construct a point  $Z$ , such that:  $XY : XZ = 1 : r$  (construction primitive)

we can derive:

- given  $M_c$  and  $G$ , it is possible to construct  $C$

## Advanced Approach: Rule Derivation

- Controlled instantiations of lemmas
- All construction rules derived from:
  - 11 **definitions** (including Wernick's notation)
  - 29 simple **lemmas**
  - 18 **construction primitives** (including elementary construction steps)
- Deriving rules is performed once, in preprocessing phase (takes approx. 20s)

## Advanced Approach: Re-evaluation

- Another corpus: construct a triangle given three lengths from the following set:
  - $|AB|$ ,  $|BC|$ ,  $|AC|$ : lengths of the sides;
  - $|AM_a|$ ,  $|BM_b|$ ,  $|CM_c|$ : lengths of the medians;
  - $|AH_a|$ ,  $|BH_b|$ ,  $|CH_c|$ : lengths of the altitudes.
- For 17 (out of total of 20) problems, additional: 2 defs, 2 lemmas, and 9 construction steps were needed
- For additional corpora, we expect less and less additions



## Output: Constructions in GCLC Form (Example)

```
% free points
point A 30 5
point B 70 5
point G 57 14
% synthesized construction
midpoint M_c A B
towards C M_c G 3
drawdashsegment M_c C
% drawing the triangle ABC
drawsegment A B
drawsegment A C
drawsegment B C
```

# Verification

- But... it is not only about synthesis/constructing!
- **Verification** (correctness proof) is also needed (not “correct by construction”)
- “If the objects ... are constructed in the given way, then they meet the specification”
- GCLC theorem provers are used (e.g. the area method, the Gröbner bases method, Wu’s method)
- The provers also provide NDG conditions

# Existence?

- 1 But... it is not only about synthesis and verification!
- 2 **Do the constructed objects exist at all?** (recall: “If the objects ... are constructed in the given way, then they meet the specification”)
- 3 Using the NDG conditions provided by the provers, we should prove that the constructed objects do exist
- 4 For this task we are planning to use our **prover for coherent logic** and generate formal proofs

## What is Coherent Logic

- CL formulae are of the form:

$$A_1(\vec{x}) \wedge \dots \wedge A_n(\vec{x}) \Rightarrow \exists \vec{y}_1 B_1(\vec{x}, \vec{y}_1) \vee \dots \vee \exists \vec{y}_m B_m(\vec{x}, \vec{y}_m)$$

$A_i$  are literals,  $B_j$  are conjunctions of literals

- No function symbols of arity greater than 0
- No negation
- Intuitionistic logic
- First used by Skolem, recently popularized by Bezem et al.
- Our system — joint work with Mladen Nikolić

## Features of CL

- Coherent logic (also: *geometric logic*) is a fragment of FOL
- The problem of deciding  $\Gamma \vdash \Phi$  is semi-decidable
- Good features:
  - certain quantification allowed
  - direct, intuitive, readable proofs
  - simple generation of formal (machine verifiable) proofs...

## Realm of CL

- A number of theories and theorems can be formulated directly and simply in CL
- Example: large fraction of Euclidean geometry belongs to CL
- Example: *for any two points there is a point between them*
- Conjectures in abstract algebra, confluence theory, lattice theory, and many more (Bezem et al)

# CL Proof System

- CL allows a simple, natural proof system (natural deduction style), based on forward ground reasoning
- Existential quantifiers are eliminated by introducing witnesses
- A conjecture is kept unchanged and proved directly (refutation, Skolemization and clausal form are not used)

## CL provers

- Euclid by Stevan Kordić and Predrag Janičić (1992)
- CL prover by Marc Bezem and Coquand (2005)
- ML prover by Berghofer and Bezem (2006)
- Geo by Hans de Nivelle (2008)
- ArgoCLP by Sana Stojanović, Vesna Pavlović and Predrag Janičić (2009)
- However, they are still not generally efficient



## Example: Proof Generated by ArgoCLP

Let us prove that  $p = r$  by reductio ad absurdum.

1. Assume that  $p \neq r$ .
2. It holds that the point  $A$  is incident to the line  $q$  or the point  $A$  is not incident to the line  $q$  (by axiom of excluded middle).
3. Assume that the point  $A$  is incident to the line  $q$ .
  4. From the facts that  $p \neq q$ , and the point  $A$  is incident to the line  $p$ , and the point  $A$  is incident to the line  $q$ , it holds that the lines  $p$  and  $q$  intersect (by axiom ax\_D5).
  5. From the facts that the lines  $p$  and  $q$  intersect, and the lines  $p$  and  $q$  do not intersect we get a contradiction.  
Contradiction.
6. Assume that the point  $A$  is not incident to the line  $q$ .
  7. From the facts that the lines  $p$  and  $q$  do not intersect, it holds that the lines  $q$  and  $p$  do not intersect (by axiom ax\_nint\_l\_l\_21).
  8. From the facts that the point  $A$  is not incident to the line  $q$ , and the point  $A$  is incident to the plane  $\alpha$ , and the line  $q$  is incident to the plane  $\alpha$ , and the point  $A$  is incident to the line  $p$ , and the line  $p$  is incident to the plane  $\alpha$ , and the lines  $q$  and  $p$  do not intersect, and the point  $A$  is incident to the line  $r$ , and the line  $r$  is incident to the plane  $\alpha$ , and the lines  $q$  and  $r$  do not intersect, it holds that  $p = r$  (by axiom ax\_E2).
  9. From the facts that  $p = r$ , and  $p \neq r$  we get a contradiction.  
Contradiction.

Therefore, it holds that  $p = r$ .

This proves the conjecture.

## On the Other Hand: CDCL Solvers

- SAT and SMT solvers are at rather mature stage
- The most efficient ones are CDCL solvers
- However, only universal quantification is allowed
- Producing readable and/or formal proofs is often challenging
- Goal: combine good features of CL and CDCL
- Goal: build an efficient CDCL prover for CL

## Three Pillars of Our Approach

The presented approach is motivated by:

**Suitability of CL:** a number of good features; potentials for obtaining readable and formal proofs

**Practical advances in CDCL SAT solving:** a huge progress in both high-level and low-level algorithmic techniques

**Theoretical advances in CDCL SAT solving:** SAT solvers described in terms of state transition systems, which enabled a deeper understanding and a rigorous analysis

# Abstract State Transition Systems for SAT

- Inspiration and starting point: transition systems for SAT
- First system: Nieuwenhuis, Oliveras, and Tinelli (2006)
- We build upon: the system by Krstić and Goel (2007)

# Krstić and Goel's System

Decide:

$$\frac{I \in L \quad I, \bar{I} \notin M}{M := M|I}$$

UnitPropag:

$$\frac{I \vee \bar{I}_1 \vee \dots \vee \bar{I}_k \in F \quad \bar{I}_1, \dots, \bar{I}_k \in M \quad I, \bar{I} \notin M}{M := M I'}$$

Conflict:

$$\frac{C = \text{no\_cflct} \quad \bar{I}_1 \vee \dots \vee \bar{I}_k \in F \quad I_1, \dots, I_k \in M}{C := \{I_1, \dots, I_k\}}$$

Explain:

$$\frac{I \in C \quad I \vee \bar{I}_1 \vee \dots \vee \bar{I}_k \in F \quad I_1, \dots, I_k \prec I}{C := C \cup \{I_1, \dots, I_k\} \setminus \{I\}}$$

Learn:

$$\frac{C = \{I_1, \dots, I_k\} \quad \bar{I}_1 \vee \dots \vee \bar{I}_k \notin F}{F := F \cup \{\bar{I}_1 \vee \dots \vee \bar{I}_k\}}$$

Backjump:

$$\frac{C = \{I, I_1, \dots, I_k\} \quad \bar{I} \vee \bar{I}_1 \vee \dots \vee \bar{I}_k \in F \quad \text{level } I > m \geq \text{level } I_j}{C := \text{no\_cflct} \quad M := M^m \bar{I}^j}$$

Forget:

$$\frac{C = \text{no\_cflct} \quad c \in F \quad F \setminus c \models c}{F := F \setminus c}$$

Restart:

$$\frac{C = \text{no\_cflct}}{M := M^{[0]}}$$

# CL state transition system (forward rules)

Decide:

$$\frac{I \in \mathcal{A}(\Sigma) \quad I \not\vdash \quad I \not\downarrow}{M := M/I \quad \Sigma := \Sigma|}$$

Intro:

$$\frac{\exists \bar{y} I \in M \quad (\exists \bar{y} I)\lambda \in \mathcal{A}(\Sigma) \quad I\lambda\lambda' \not\vdash \text{ for any } \lambda'}{M := M \frown I[y_1 \mapsto c^{\ell+1}, \dots, y_k \mapsto c^{\ell+k}]\lambda \quad \Sigma := \Sigma \frown c^{\ell+1}, \dots, c^{\ell+k} \quad \ell := \ell + k}$$

Unit propagate left:

$$\frac{\mathcal{P} \cup \{I\} \Rightarrow \mathcal{Q} \in^{n_1} \Gamma \quad \mathcal{P} \Rightarrow \mathcal{Q} \downarrow_{\lambda}^m \quad m(\mathcal{P} \cup \mathcal{Q}) \subseteq^{n_2} M \quad \bar{I}\lambda \not\vdash \quad \bar{I}\lambda \not\downarrow}{M := M \frown^{\max(n_1, n_2)} \bar{I}\lambda}$$

Unit propagate right:

$$\frac{\mathcal{P} \Rightarrow \mathcal{Q} \cup \{I\} \in^{n_1} \Gamma \quad \mathcal{P} \Rightarrow \mathcal{Q} \downarrow_{\lambda}^m \quad m(\mathcal{P} \cup \mathcal{Q})^{n_2} \subseteq M \quad I\lambda \not\vdash \quad I\lambda \not\downarrow}{M := M \frown^{\max(n_1, n_2)} I\lambda}$$

Branch end:

$$\frac{C_2 = \{\text{no\_cflct}\} \quad \mathcal{P} \Rightarrow \mathcal{Q} \in \Gamma \quad \mathcal{P} \Rightarrow \mathcal{Q} \downarrow}{C_1 := \mathcal{P} \quad C_2 := \mathcal{Q}}$$

# CL state transition system (backward rules)

Explain left  $\forall$ :

$$\frac{C_1 \Rightarrow C_2 \downarrow^m \quad I \in m(C_1) \quad S = m^{-1}(I) \quad S \Rightarrow \forall \vec{x} p(\vec{v}, \vec{x}) \quad \mathcal{P} \Rightarrow \mathcal{Q} \cup \{p(\vec{v}', \vec{x}')\} \in \Gamma \quad \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'}}{C_1 := (\forall \vec{x}' \mathcal{P} \cup (C_1 \setminus S))\lambda \quad C_2 := (\exists \vec{x}' \mathcal{Q} \cup C_2)\lambda}$$

Explain left  $\exists$ :

$$\frac{C_1 \Rightarrow C_2 \downarrow^m \quad I \in m(C_1) \quad S = m^{-1}(I) \quad S \Rightarrow_{\sigma} p(\vec{v}, \vec{x}) \quad \mathcal{P} \Rightarrow \mathcal{Q} \cup \{\exists \vec{x}' p(\vec{v}', \vec{x}')\} \in \Gamma \quad \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'}}{C_1 := (\mathcal{P} \cup \forall \vec{x}(C_1 \sigma \setminus S \sigma))\lambda \quad C_2 := (\mathcal{Q} \cup \exists \vec{x}(C_2 \sigma))\lambda}$$

Explain right  $\forall$ :

$$\frac{C_1 \Rightarrow C_2 \downarrow^m \quad I \in m(C_2) \quad S = m^{-1}(I) \quad S \Rightarrow_{\sigma} p(\vec{v}, \vec{x}) \quad \{\forall \vec{x}' p(\vec{v}', \vec{x}')\} \cup \mathcal{P} \Rightarrow \mathcal{Q} \in \Gamma \quad \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'}}{C_1 := (\mathcal{P} \cup \forall \vec{x}(C_1 \sigma))\lambda \quad C_2 := (\mathcal{Q} \cup \exists \vec{x}(C_2 \sigma \setminus S \sigma))\lambda}$$

Explain right  $\exists$ :

$$\frac{C_1 \Rightarrow C_2 \downarrow^m \quad I \in m(C_2) \quad S = m^{-1}(I) \quad S \Rightarrow \exists \vec{x} p(\vec{v}, \vec{x}) \quad \{p(\vec{v}', \vec{x}')\} \cup \mathcal{P} \Rightarrow \mathcal{Q} \in \Gamma \quad \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'}}{C_1 := (\forall \vec{x}' \mathcal{P} \cup C_1)\lambda \quad C_2 := (\exists \vec{x}' \mathcal{Q} \cup (C_2 \setminus S))\lambda}$$

Learn:

$$\frac{C_2 \neq \{no\_cflct\} \quad C_1 \Rightarrow C_2 \notin \Gamma}{\Gamma := \Gamma \frown C_1 \Rightarrow C_2}$$

Backjump:

$$\frac{C_1 \Rightarrow C_2 \in \Gamma \quad C_1 \Rightarrow C_2 \downarrow^m \quad I \in m(C_1) \quad S = m^{-1}(I) \quad C_1 \setminus S \Rightarrow C_2 \downarrow_{\lambda}^{m'} \quad m' \subseteq m \quad m'(C_1 \setminus S \cup C_2) \subseteq^n M \quad I \in^{n'} M \quad n \leq t < n' \quad S\lambda \Rightarrow I'}{M := M^{t \frown n'} \quad \Sigma := \Sigma^t \quad C_1 := \emptyset \quad C_2 := \{no\_cflct\}}$$

## Basic properties

- Sound
- Complete with additional rule for iterative deepening



## Example of system operation

(Ax1)  $p(x, y) \wedge q(x, y) \Rightarrow \perp$

(Ax2)  $s(x) \Rightarrow \exists y q(x, y)$

(Ax3)  $s(x) \vee q(y, y)$

(Conj)  $(\forall x \forall y p(x, y)) \Rightarrow \perp$

Rule applied	$\Sigma$	$\Gamma \setminus \mathcal{A}\mathcal{X}$ (lemmas)	$M$	$\mathcal{C}_1 \Rightarrow \mathcal{C}_2$
Decide	$a$	$\emptyset$	$p(x, y)$	$\emptyset \Rightarrow \{no\_cflct\}$
	$a$	$\emptyset$	$p(x, y)   s(x)$	$\emptyset \Rightarrow \{no\_cflct\}$
U.p.r. (Ax2)	$a$	$\emptyset$	$p(x, y)   s(x), \exists y q(x, y)$	$\emptyset \Rightarrow \{no\_cflct\}$
Intro	$a   b$	$\emptyset$	$p(x, y)   s(x), \exists y q(x, y), q(a, b)$	$\emptyset \Rightarrow \{no\_cflct\}$
B.e. (Ax1)	$a   b$	$\emptyset$	$p(x, y)   s(x), \exists y q(x, y), q(a, b)$	$p(x, y) \wedge q(x, y) \Rightarrow \perp$
E.l. $\exists$ (Ax2)	$a   b$	$\emptyset$	$p(x, y)   s(x), \exists y q(x, y), q(a, b)$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$
Learn	$a   b$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$	$p(x, y)   s(x), \exists y q(x, y), q(a, b)$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$
B.j.	$a$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$	$p(x, y), \overline{s(x)}$	$\emptyset \Rightarrow \{no\_cflct\}$
U.p.r. (Ax3)	$a$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$	$p(x, y), \overline{s(x)}, q(y, y)$	$\emptyset \Rightarrow \{no\_cflct\}$
B.e. (Ax1)	$a$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$	$p(x, y), \overline{s(x)}, q(y, y)$	$p(x, y) \wedge q(x, y) \Rightarrow \perp$
E.r. (Ax3)	$a$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$	$p(x, y), \overline{s(x)}, q(y, y)$	$p(x, x) \Rightarrow s(z)$
E.r. (lemma)	$a$	$\forall y p(x, y) \wedge s(x) \Rightarrow \perp$	$p(x, y), \overline{s(x)}, q(y, y)$	$p(x, x) \wedge \forall y p(z, y) \Rightarrow \perp$

## Forward chaining proofs

$$\frac{\frac{s(x) \vee q(y, y) \quad p(x, y) \wedge q(x, y) \Rightarrow \perp}{p(x, x) \Rightarrow s(z)} \quad \frac{s(x) \Rightarrow \exists y q(x, y) \quad p(x, y) \wedge q(x, y) \Rightarrow \perp}{\forall y p(x, y) \wedge s(x) \Rightarrow \perp}}{p(x, x) \wedge \forall y p(z, y) \Rightarrow \perp}$$

$$\frac{s(x) \Rightarrow \exists y q(x, y) \quad p(x, y) \wedge q(x, y) \Rightarrow \perp}{\forall y p(x, y) \wedge s(x) \Rightarrow \perp} \quad \frac{\frac{\frac{\perp \vdash \perp}{q(a, b) \vdash \perp} \Rightarrow (Ax1)}{\exists y q(a, y) \vdash \perp} \exists}{\mathcal{A}\mathcal{X}, p(a, y), s(a) \vdash \perp} \Rightarrow (Ax2)$$

$$\frac{s(x) \vee q(y, y) \quad p(x, y) \wedge q(x, y) \Rightarrow \perp}{p(x, x) \Rightarrow s(z)} \quad \frac{\frac{s(b) \vdash s(b)}{s(x) \vdash s(b)} Inst \quad \frac{\frac{\perp \vdash s(b)}{q(a, a) \vdash s(b)} \Rightarrow (Ax1)}{q(y, y) \vdash s(b)} Inst}{\mathcal{A}\mathcal{X}, p(a, a) \vdash s(b)} \vee (Ax3)$$

# Forward chaining proofs

$$\frac{\frac{\perp \vdash \perp}{q(a, b) \vdash \perp} \Rightarrow (Ax1)}{\exists y q(a, y) \vdash \perp} \exists \Rightarrow (Ax2)$$

+

$$\frac{\frac{s(b) \vdash s(b)}{s(x) \vdash s(b)} Inst \quad \frac{\perp \vdash s(b)}{q(a, a) \vdash s(b)} \Rightarrow (Ax1)}{\mathcal{A}\mathcal{X}, p(a, a) \vdash s(b)} Inst \vee (Ax3)$$

↓

$$\frac{\frac{\frac{\perp \vdash \perp}{p(a, b) \vdash \perp} \Rightarrow (Ax1)}{q(a, b) \vdash \perp} Inst \quad \frac{\perp \vdash \perp}{p(a, a) \vdash \perp} \Rightarrow (Ax1)}{\exists y q(a, y) \vdash \perp} \exists \Rightarrow (Ax2) \quad \frac{q(a, a) \vdash \perp}{q(y, y) \vdash \perp} Inst$$

$$\frac{\frac{s(a) \vdash \perp}{s(x) \vdash \perp} Inst \quad \mathcal{A}\mathcal{X}, p(x, y) \vdash \perp}{\mathcal{A}\mathcal{X}, p(x, y) \vdash \perp} \vee (Ax3)$$

## Readable proof

- Assume  $\forall x \forall y p(x, y)$ .
- By (Ax3), it holds  $\forall x s(x)$  or  $\forall y q(y, y)$ .
- Assume  $\forall x s(x)$ .
  - From  $\forall x s(x)$ , it holds  $s(a)$ .
  - By (Ax2), it holds  $\exists y q(a, y)$ .
  - From  $\exists y q(a, y)$ , there is  $b$  such that  $q(a, b)$ .
  - From  $\forall x \forall y p(x, y)$ , it holds  $p(a, b)$ .
  - By (Ax1), this leads to contradiction.
- Assume  $\forall y q(y, y)$ .
  - From  $\forall y q(y, y)$ , it holds  $q(a, a)$ .
  - From  $\forall x \forall y p(x, y)$ , it holds  $p(a, a)$ .
  - By (Ax1), this leads to contradiction.

## Related work

- Euclid (Janičić, Kordić) — CL-geometry, simple backtracking, ground reasoning, iterative deepening
- Bezem's CL prover (Bezem) — CL, simple backtracking, ground reasoning, breadth first search
- Geometric resolution and Geo (de Nivelles) — CL-like, backtracking with lemma learning, ground reasoning
- ArgoCLP (Stojanović, Pavlović, Janičić) — CL, simple backtracking, ground reasoning, iterative deepening
- Model evolution calculus and Darwin (Baumgartner, Tinelli, Fuchs, Pelzer) — clausal fragment, CDCL-style procedure
- EPR (Piskač, de Moura, Bjorner) — clausal fragment without function symbols, CDCL-style procedure

## Conclusions and future work

- Goal — integrated framework for:
  - Solving construction problems
  - Visualizing constructions
  - Proving that the construction objects exist
  - Proving that the constructed objects meet the specification